

NCCARF and the Australian Climate Change Adaptation Research
Network for Settlements and Infrastructure present:

Learning from UKCIP - supporting adaptation to the unavoidable impacts of climate change in the UK

Kate Lonsdale - UK Climate Impacts Program and
VCCCAR Visiting Fellow

Date: Thursday 29th November
Time: 4.45pm to 6.00pm followed by refreshments
Venue: Conference Room 2, Level 7,
UNSW CBD Campus, 1 O'Connell St, Sydney
RSVP: <http://lonsdalesydney.eventbrite.com.au/>

UKCIP was set up in 1997 as an organisation that could facilitate 'bottom-up', stakeholder-driven research in an integrated manner to yield the information needed for UK organisations to adapt to climate change. In doing this UKCIP is considered to be the first organisation of its kind in the world, with its approaches, methods, projects and ground-breaking work in stakeholder-led engagement being widely referenced. UKCIP is recognised as having played a major role in increasing awareness of the need to adapt and in driving forward action on the ground.

2012 marked the end of a 14-year relationship with Defra as UKCIP's major funding partner and the transfer of UKCIP's main function to the UK Environment Agency. This presentation reflects on the history of the organisation, outlines some of its achievements and how its activities evolved over time with the changing adaptation landscape in the UK. It also explores the role of a boundary organisation in supporting adaptation in practice.

About Kate:

Kate's work focuses on understanding adaptation in practice including what it means to be well adapting, how you build adaptive capacity and what supports and constrains processes of adaptation. She has worked on adaptation as a researcher, trainer, facilitator, consultant, mentor, evaluator and in an advisory capacity for the last 16 years in both developed and developing country contexts. She has been working with the UK Climate Impacts Programme since 2008 and is also an associate of the Stockholm Environment Institute.

Image: Timothy Newton-Syms